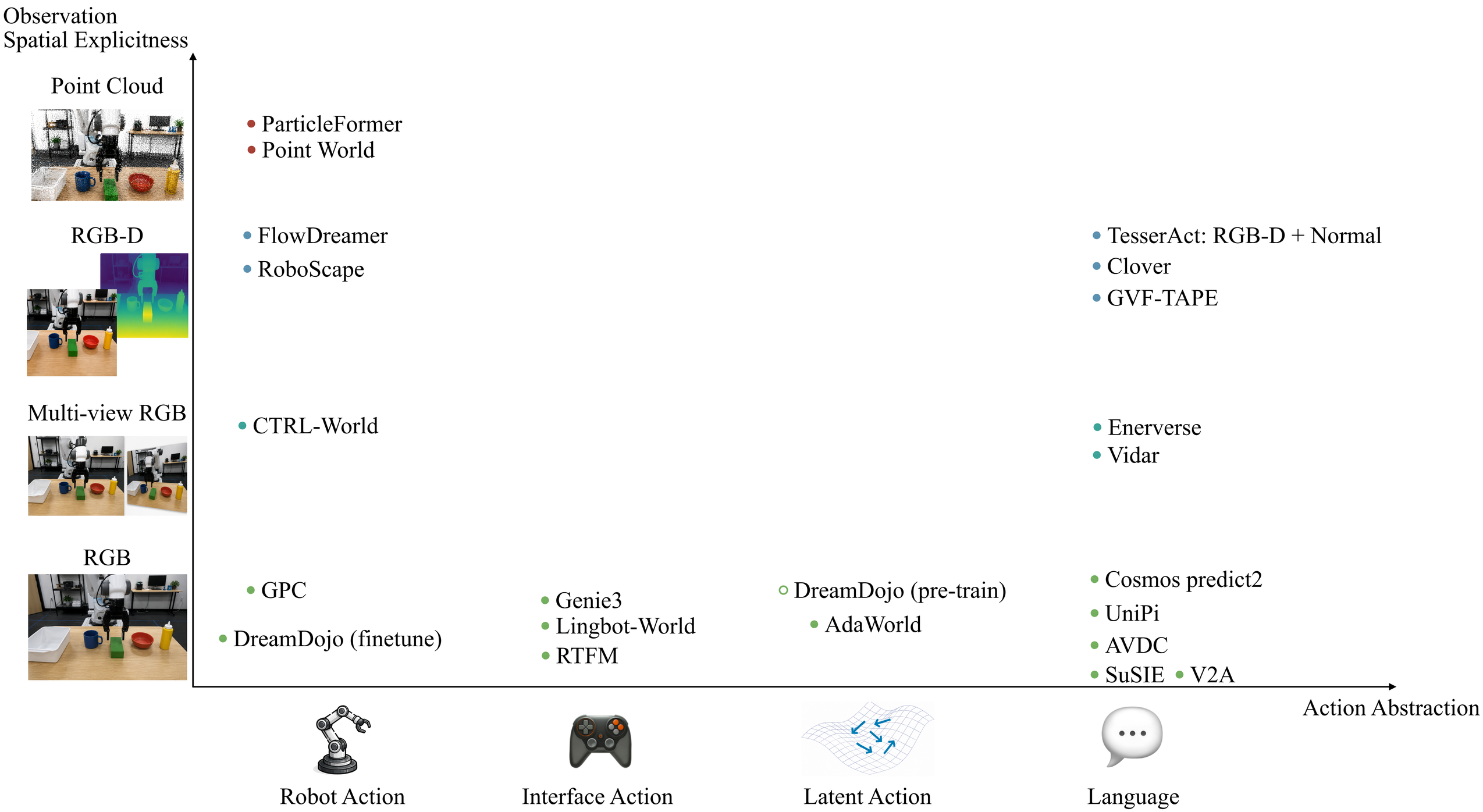
Observation
Spatial Explicitness
Point Cloud
ParticleFormer
Point World
RGB-D
FlowDreamer
RoboScape
TesserAct: RGB-D + Normal
Clover
GVF-TAPE
Multi-view RGB
CTRL-World
Enerverse
Vidar
RGB
GPC
DreamDojo (finetune)
Genie3
Lingbot-World
RTFM
DreamDojo (pre-train)
AdaWorld
Cosmos predict2
UniPi
AVDC
SuSIE
V2A
Action Abstraction
Robot Action
Interface Action
Latent Action
Language